

Thesis for Master's Degree

The Title

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School of Mechatronics

Gwangju Institute of Science and Technology

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The Title

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November 30, 2014

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Dedicated to
my family.

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Abstract

In recent years,

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최근 제어 시스템

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Chapter 1

Introduction

1.1 BibTeX

Compile in a sequence of pdfLaTeX \rightarrow BibTeX \rightarrow pdfLaTeX \rightarrow pdfLaTeX [1] to get the final document.

1.2 Equation

$$\dot{x} = f(t, x). \tag{1.1}$$

From the system in (1.1)...

1.3 Theorem

Theorem 1.1. *The equilibrium point of...*

Proof. We have

$$\dot{V} \leq 0.$$

As a consequence, ...

□

1.4 Figure

Never mind the location of Figure 1.1.

Table 1.1: ...

7C0	hexadecimal
3700	octal
11111000000	binary
1984	decimal

1.5 Table

Never mind the location of Table 1.1.

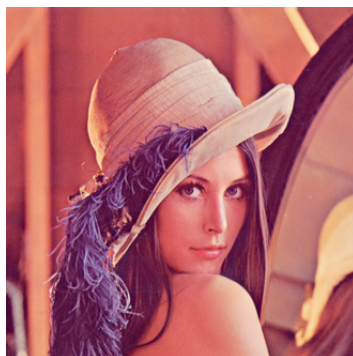


Figure 1.1: ...

Chapter 2

Conclusion

Bibliography

1. B. D. O. Anderson, C. Yu, B. Fidan, and J. M. Hendrickx, “Rigid graph control architectures for autonomous formations,” *IEEE Control Systems Magazine*, vol. 28, no. 6, pp. 48–63, 2008.

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